

Autonomous Underwater Swarms: docking problem and control strategies

*Titouan BELIER, Lionel Lapierre*

Underwater Object Manipulation by a Fleet of Robots via an Overconstrained Tensegrity Structure

*Taddeo Guerin, Viel Christophe, Lionel Lapierre*

AI-based Human Detection in Indoor Environments using IR-UWB radar

*Zaynab Baydoun, Roua Youssef, Emanuel Radoi, Stéphane Azou, Tina Yaacoub*

Analysis of Necessary Optimality Conditions for Impulsive Lotka-Volterra Control Systems

*Paulin Bruneau, Piernicola Bettiol, Jérémy Rouot*